

**Amendments to the Specification:**

Please replace previously-amended paragraph [0028] of Applicant's published application with the following amended paragraph:

[0028] As non-limitative example, the robotic system 4 includes at least two numerical control rails axes. The system 4 is composed of a skid, movable along a horizontal rail axis 27, which, in turn, conveys a vertical rail axis 28 that is fitted with pick-up device 18 and the end part of an optical sensor 10 to obtain a return signal of the precision of the positioning of the gripper 18 in relation to the location 17. As shown in Fig. 1, the horizontal rail 27 extends entirely across the stacked disks 9, with a portion thereof extending above the opening 7 of the shelf 6.